

Template:Networking rutc manual input output status

ioman.gpio.din1 - 4PIN input
ioman.gpio.dout1 - 4PIN output

Call command **ubus call value status** :

```
root@Teltonika-{{{name}}}:~# ubus call ioman.gpio.din1 status
{
    "value": "0",
    "direction": "in",
    "bi_dir": false,
    "invert_input": false
}
```

- **din1** is the input:
 - "value": "**0**" means low level state.
 - "value": "**1**" means high level state.
- **dout1** is the output:
 - "value": "**0**" means low level state.
 - "value": "**1**" means high level state.