

RUT906 GPS

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The information in this page is updated in accordance with firmware version [RUT9M_R_00.07.07.1](#).

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Summary

The **Global Positioning System (GPS)** is a space-based radionavigation system. This page is an overview of the GPS service in RUT906 devices.

General

The **General** is used to enable the GPS service and the support for different types satellites. Once you turn on GPS, you can check the [Map](#) page in order to see if the device has obtained a GPS fix. It is very important to attach the GPS antenna on the device and place it outside (not inside of a building). The device will not be likely to obtain a GPS fix otherwise.

The figure below is an example of the General page and the table below provides information on the fields contained in that page:

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Field	Value	Description
Enabled	off on; default: off	Turns the GPS service on or off.

*Changing these options requires a modem reboot. Therefore, if you make changes to these options and save them, the device will lose cellular connectivity for about 30 seconds.

Map

The **Map** page displays the device's current coordinates and position on the map. To see the device's location on the map, make sure to attach the GPS antenna on the device and enable GPS in the [General](#) page.

The figure below is an example of the Map page:



NMEA

The **NMEA** page is used to configure settings related to NMEA sentence collecting and forwarding.

NMEA forwarding

The **NMEA forwarding** section is used to configure and enable NMEA forwarding. The figure below is an example of the NMEA forwarding section and the table below provides information on the fields contained in that section:



Field	Value	Description
Enabled	off on; default: off	Turns NMEA forwarding on or off.
Hostname	ip host; default: none	IP address or hostname of the server to which NMEA data will be forwarded.
Protocol	TCP UDP; default: TCP	Protocol that will be used to send NMEA data.
Port	integer [0..65535]; default: 8500	Port number off the server to which NMEA data will be forwarded.
Contain connection	off on; default: off	Contains active session with the remote server if turned on.
Select prefix	Custom None Serial Mac address IMEI; default: None	Prefix is added to the NMEA sentence before it is transmitted.

NMEA forwarding cache

The device **caches NMEA forwarding** information if NMEA forwarding is enabled. This section is used to select the memory type where the cache will be stored and the maximum amount of data that will be saved:



Field	Value	Description
Save cache in	RAM Memory FLASH Memory; default: RAM Memory	Selects which type of memory will be used for storing NMEA forwarding cache.
Maximum sentences	integer; default: 5000	Maximum amount of NMEA sentences that will be saved in the cache before older entries are deleted and replaced by new ones.
File	filepath; default: none	Location of the file where NMEA forwarding cache information will be stored. This field becomes visible only when the selected memory type is "flash".

NMEA collecting

The **NMEA collecting** section is used to enable NMEA sentence gathering and storing. The figure below is an example of the NMEA collecting section and the table below provides information on the fields contained in that section:



Field	Value	Description
Enabled	off on; default: off	Turns NMEA sentence collecting on or off.
File	filepath; default: none	Location of the file where NMEA sentences will be stored. This field becomes visible only when NMEA collecting is enabled.

NMEA sentence settings

The **NMEA sentence settings** section provides the possibility to configure which NMEA sentences will be forwarded or collected and at what frequency. The figure below is an example of the NMEA sentence settings section and the table below provides information on the fields contained in that section:



Field	Value	Description
Forwarding enabled	off on; default: off	Enables forwarding for the adjacent NMEA sentence.
Forwarding interval	positive integer; default: 5	NMEA sentence forwarding frequency in seconds.
Collecting enabled	off on; default: off	Enables collecting for the adjacent NMEA sentence.
Collecting interval	positive integer; default: 5	NMEA sentence collecting frequency in seconds.

NMEA sentence reference table:

NMEA sentence name	Description
GPGLW	Number of GPS satellites in view.
GPGLA	GPS fix data.
GPVTG	GPS track made good and speed relative to the ground.
GPRMC	Recommended minimum specific GPS/Transit data.


GP GS	GPS DOP and active satellites.
GN GS	GLONASS DOP and active satellites.
GL GS	Number of GLONASS satellites in view.
GNG S	GNSS position fix from more than one constellation (e.g., GPS + GLONASS).
GAG S	Number of Galileo satellites in view.
GARM C	Recommended minimum specific for Galileo data.
GAG G	Galileo fix data.
GAG S	Galileo DOP and active satellites.
GAV TG	Galileo track made good and speed information relative to the ground.
PQG S	Detailed satellite data (used in BeiDou and QZSS (Quectel Quirk) sentences).
PQG S	Overall satellite data (used in BeiDou and QZSS (Quectel Quirk) sentences).
GBG S	Detailed satellite data (used in BeiDou sentences).
GBG S	BeiDou DOP and active satellites.
GQG S	Detailed QZSS satellite data (QZSS regional GPS augmentation system (Japan)).
GQG S	QZSS DOP and active satellites (QZSS regional GPS augmentation system (Japan)).

HTTPS

The **HTTPS** page can be used to configure data sending to an HTTP(S) server.


HTTPS/HTTP server settings

The HTTPS/HTTP Server Settings section is used to enable GPS data sending to an HTTP or HTTPS server.



Field	Value	Description
Enabled	off on; default: off	Turns data sending to HTTP/HTTPS server on or off.
URL	url string; default: none	URL of the remote server (ex. example.com/xxxx).
Interval	integer; default: none	Interval on which collected NMEA sentences should be forwarded.

TAVL settings

The **TAVL settings** section is used to select which data will be sent to the TAVL server: 

Field	Value	Description
Signal	off on; default: off	Includes GSM signal strength information in the GPS data sent to server.
Input (3)	off on; default: off	Includes din1 status information in the GPS data sent to server.
Digital Input (1)	off on; default: off	Includes din2 status information in the GPS data sent to server.
Isolated Input (2,7)	off on; default: off	Includes iio status information in the GPS data sent to server.
Analog Input (6,9)	off on; default: off	Includes Adc0 status information in the GPS data sent to server.
Analog Current Loop (6,9)	Current Percent ; off on; default: Current ; off	Includes Acl0 Current/Percent information in the GPS data sent to server.

HDOP	off on; default: off	Includes horizontal dilution of precision in the GPS data sent to server.
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AVL

The **AVL** page is used to set up GPS data sending to an AVL server.

AVL server settings

The **AVL server settings** section is used to configure the main parameters of data sending to an AVL server. The figure below is an example of the AVL Server Settings section and the table below provides information on the fields contained in that section:



Field	Value	Description
Enabled	off on; default: off	Turns data sending to AVL server on or off.
Retry on Fail	off on; default: off	Turn retries in case of a failed attempts on or off. When turned on, the device will try to send the same data to the server until the transmission is successful.
Hostname	ip host; default: 192.168.0.1	IP address or hostname of an AVL server.
Protocol	TCP UDP; Default: TCP	Protocol that will be used for communication with the AVL server.
Port	integer [0..65535]; default: 8501	TCP/UDP port number of the AVL server to which the device will be connecting.
Don't Contain Connection	off on; default: off	When turned on, handles each AVL packet iteration as a new connection. When turned off, connects once and uses the same socket for future communication.
Static Navigation	off on; default: off	Stop collecting NMEA data if object is stationary. Ignores data when speed equals to 0 or same as previous coordinates (rounded to 4 decimals).

Main rule

The **Main rule** section defines how and when GPS data will be collected and sent to a specified AVL server. Refer to the figure and table below for information on the configuration fields of Main Rule.



Field	Value	Description
Enable	off on; default: on	Turns the main rule on or off.

Rule priority	Low priority level High priority level Panic priority level Security priority level; default: Low priority level	The rule's priority. Different priority settings add different flags to event packets, so they can be displayed differently in the receiving system. The device sends data of higher priority first. Priority levels from highest to lowest are as follows: 1. Security 2. Panic 3. High 4. Low
Collect period	integer [1..999999]; default: 5	How often (in seconds) data will be collected.
Min distance	integer [1..999999]; default: 50	Minimum distance change (in meters) before sending records.
Min angle	integer [1..360]; default: 50	Minimum angle change (in degrees) before sending records.
Min accuracy	integer [1..999999]; default: 10	Minimum accuracy (in meters) required before saving record. The lower the accuracy value, the better.
Min saved records	integer [1..32]; default: 20	Minimum amount of gathered records before sending.
Send period	integer [0..999999]; default: 60	How often (in seconds) gathered data is sent.

Secondary rules

The **Secondary rules** section provides you with the possibility to create additional data sending rules. The difference from the main rule is that the secondary rules only send data when the device uses a specified type of WAN and when the digital isolated output is in the specified state.

Refer to the figure and table below for information on the configuration fields of the Secondary rules section.



Field	Value	Description
Enable	off on; default: off	Turns the secondary rule on or off.
WAN	Mobile Both Mobile Home Mobile Roaming Wired; default: Mobile Home	Selects which type of WAN will trigger the rule.
Ignore	off on; default: off	If enabled, the rule ignores state of input.
IO level	Low level High level Both; default: High level	Selects which input state will trigger the rule.
IO type	GPIO ADC ACL; default: GPIO	Selects input type.
IO name	Input (3) Input (1) Isolated Input (2,7); default: Input (1)	Selects which specific input will trigger the rule.

Rule priority	Low priority level High priority level Panic priority level Security priority level; default: High priority level	The rule's priority. Different priority settings add different flags to event packets, so they can be displayed differently in the receiving system. The device sends data of higher priority first. Priority levels from highest to lowest are as follows: 1. Security 2. Panic 3. High 4. Low
Collect period	integer [1..999999]; default: 10	How often (in seconds) data will be collected.
Min distance	integer [1..999999]; default: 25	Minimum distance change (in meters) before sending records.
Min angle	integer [1..360]; default: 25	Minimum angle change (in degrees) before sending records.
Min accuracy	integer [1..999999]; default: 10	Minimum accuracy (in meters) required before saving record. The lower the accuracy value, the better.
Min saved records	integer [1..32]; default: 10	Minimum amount of gathered records before sending.
Send period	integer [0..999999]; default: 10	How often (in seconds) gathered data is sent.

TAVL settings

The **TAVL settings** section is used to select which data will be sent to the TAVL server:



Field	Value	Description
Signal	off on; default: off	Includes GSM signal strength information in the GPS data sent to server.
Din1	off on; default: off	Includes Din1 status information in the GPS data sent to server.
Din2	off on; default: off	Includes Din2 status information in the GPS data sent to server.
Din2	off on; default: off	Includes Din2 status information in the GPS data sent to server.
Iio	off on; default: off	Includes Iio status information in the GPS data sent to server.
Adc0	off on; default: off	Includes Adc0 status information in the GPS data sent to server.
Acl0	Current Percent ; off on; default: Current ; off	Includes Acl0 Current/Percent information in the GPS data sent to server.

AVL I/O

The **AVL I/O** tab provides you with the possibility to configure input rules.

Input Rules

The **Input Rules** section displays existing input rules. To create a new input rule click the 'Add'

button.



After this you should be redirected to configuration page of the newly added rule, which should look similar to this:



Field	Value	Description
Enable	off on; default: on	Turns the input rule on or off.
Input type	Analog Current Loop (6,9) Analog Input (6,9) Input (3) Digital Input (1) Isolated Input (2,7); default: Analog Current Loop (6,9)	Select type on your own intended configuration.
ACL Property	Current Percent; default: Current	Select which property - ampere or percentage the condition listens to.
Min current	float [4..20]; default: none	Specifies minimum current of the range. Values between 4-20mA.
Max current	float [4..20]; default: none	Specifies maximum current of the range. Values between minimum-20mA.
Min voltage	float [0..40]; default: none	Specify minimum voltage range.
Max voltage	float [0..40]; default: none	Specify maximum voltage range.
Trigger	Inside range Outside range ; Inside range Outside range ; Input active Input low Both; default: Inside range; Inside range; Input active	Inside range - Input voltage falls in the specified region, Outside range - Input voltage drops out of the specified region ; Select trigger event for your own intended configuration.
Priority	Low High Panic Security; default: Low	The rule's priority. Different priority settings add different flags to event packets, so they can be displayed differently in the receiving system. The device sends data of higher priority first.

GPS Geofencing

A **geofence** is a virtually defined boundary for a real-world geographic area. The GPS Geofencing page provides you with the possibility to set this custom area and apply rules that will inform you when the device leaves or enters the geofence.

To create a new geofence area, enter a custom name for it and click the 'Add' button. A new geofence area configuration with the given name should appear in the "Geofencing" list. Click the button that looks like a pencil next to it to begin editing.

The figure below is an example of GPS Geofencing configuration and the table below provides information related to that configuration:



Field	Value	Description
Enable	off on; default: off	Turns the Geofence rule on or off.

Longitude (X)	degrees [-180.000000..180.000000]; default: 0.000000	East-west position of a point on the Earth's surface. Combining this and the Latitude information will produce a point on the world map that will serve as the center of the geofence area.
Latitude (Y)	degrees [-90.000000..90.000000]; default: 0.000000	North-south position of a point on the Earth's surface. Combining this and the Longitude information will produce a point on the world map that will serve as the center of the geofence area.
Radius	integer [1..999999]; default: 200	Radius (in meters) of the geofence area.
Generate event on	Exit Enter Enter/exit; default: Exit	Specifies whether the rule should be triggered when the device enters the geofence area, leaves it or on both events.
Switch profile	configuration profiles; default: none	Selects a profile to switch to on this geofencing event.
Get current coordinates	- (interactive button)	Obtains the device's current coordinates and places them in the Longitude and Latitude fields.