

TRB145 Serial Utilities

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The information in this page is updated in accordance with firmware version [TRB1_R_00.07.08.2](#).

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Summary

The **Serial Utilities** page is used to make serial communication configurations of different types. This manual page provides an overview of the Serial Utilities page in TRB145 devices.

General information

RS485

Connector pinout

Below is a depiction of the RS485 connector pins:

RS485 connector pinout		
Pin	Name	Description
1	D_N	Driver negative signal
2	R_N	Receiver negative signal
3	GND	Device ground
4	D_P	Driver positive signal
5	R_P	Receiver positive signal
6	NC	Power input 9-30 VDC

Cable type

Recommended cable parameters:

PARAMETER	VALUE
Cable Type	22-24 AWG, 2 - pair (used for full-duplex networks) or 1-pair (used for half duplex networks). One additional wire for ground connection is needed
Characteristic cable Impedance	120 Ω @ 1MHz
Capacitance (conductor to conductor)	36 pF/m
Propagation Velocity	78% (1.3 ns/ft)

Maximum data rate vs. transmission line length

The RS485 standard can be used for network lengths up to 1200 meters, but the maximum usable data rate decreases as the transmission length increases. A device operating at the maximum data transfer rate (10 Mbps) is limited to a transmission length of about 12 meters, while a distance up to 1200 meters can be achieved at 100 Kbps. A rough relation between maximum transmission length and data rate can be calculated using this approximation:



Where:

- L_{max} - maximum cable length in meters.
- **DR** - maximum data rate in bits per second.

Twisted pair is the preferred cable type for RS485 networks. Twisted pair cables pick up noise and other electromagnetically induced voltages as common mode signals, which are rejected by the differential receivers.

2-Wire and 4-Wire Networks

Below is an example of a 4-wire network electrical connection. There are 3 devices shown in the example. One of the devices is the "master" and other two are "slaves". Termination resistors (120 Ω each) are placed at each cable end. Four-wire networks consists of one master with its transmitter connected to each of the slaves' receivers on one twisted pair. The slave transmitters are all connected to the master receiver on a second twisted pair:



Example 2-wire network electrical connection: to enable a 2-wire RS485 configuration you need to connect D_P to R_P and D_N to R_N on the device's RS485 socket. Termination resistors are placed at each cable end (120 Ω each):



Modem Control

The **Modem** serial type is used to manage modem functionality which could be accessed using shell interface. For this purpose you may want use CR/LF (Carriage Return, Line Feed) capable applications like PuTTY on Windows and microcom, minicom, cutecom or similar applications on Linux.



Field	Value	Description
Enable	off on; default: off	Turns the instance on or off.
Name	string; default: none	Instance name, generated by the user when first creating the configuration.
Device	RS485; default: RS485	Specifies which serial port will be used for serial communication.
Baud rate (RS485)	integer [300..230400]; default: 9600	Data rate for serial data transmission (in bits per second (bps)).
Data bits	8; default: 8	Number of data bits for each character.
Stop bits	1 2; default: 1	Stop bits sent at the end of every character allow the receiving signal hardware to detect the end of a character and to resynchronise with the character stream. Electronic devices usually use one stop bit. Two stop bits are required if slow electromechanical devices are used.
Parity	None Odd Even Mark Space; default: None	In serial transmission, parity is a method of detecting errors. An extra data bit is sent with each data character, arranged so that the number of 1 bits in each character, including the parity bit, is always odd or always even. If a byte is received with the wrong number of 1s, then it must have been corrupted. However, an even number of errors can pass the parity check. <ul style="list-style-type: none"> • None (N) - no parity method is used. • Odd (O) - the parity bit is set so that the number of "logical ones (1s)" has to be odd. • Even (E) - the parity bit is set so that the number of "logical ones (1s)" has to be even.
Flow control	None; default: None	In many circumstances a transmitter might be able to send data faster than the receiver is able to process it. To cope with this, serial lines often incorporate a "handshaking" method, usually distinguished between hardware and software handshaking.

Mode	Partial control Full control; default: Partial control	Specifies modem control mode. <ul style="list-style-type: none"> • Partial control- enables modem control with AT commands, mobile connection will be controlled by RUTOS. • Full control- enables modem control with AT commands, mobile connection will be controlled by user.
RS485: Full Duplex	off on; default: off	Turns Full Duplex mode on or off. This option is available only on the RS485 device.
Start up message	string; default: none	Message to print to serial device when modem control is ready.

Console

Console mode requires no further configuration than the settings above and is used as a direct-access method to the device's shell interface. For this purpose you may want use such applications as PuTTY on Windows and microcom, minicom, picocom or similar applications on Linux.




Field	Value	Description
Enable	off on; default: off	Turns the instance on or off.
Name	string; default: none	Instance name, generated by the user when first creating the configuration.
Device	RS485; default: RS485	Specifies which serial port will be used for serial communication.
Baud rate (RS485)	integer [300..230400]; default: 9600	Data rate for serial data transmission (in bits per second (bps)).
Data bits	8; default: 8	Number of data bits for each character.
Stop bits	1 2; default: 1	Stop bits sent at the end of every character allow the receiving signal hardware to detect the end of a character and to resynchronize with the character stream. Electronic devices usually use one stop bit. Two stop bits are required if slow electromechanical devices are used.
Parity	None Odd Even Mark Space; default: None	In serial transmission, parity is a method of detecting errors. An extra data bit is sent with each data character, arranged so that the number of 1 bits in each character, including the parity bit, is always odd or always even. If a byte is received with the wrong number of 1s, then it must have been corrupted. However, an even number of errors can pass the parity check. <ul style="list-style-type: none"> • None (N) - no parity method is used. • Odd (O) - the parity bit is set so that the number of "logical ones (1s)" has to be odd. • Even (E) - the parity bit is set so that the number of "logical ones (1s)" has to be even.
Flow control	None; default: None	In many circumstances a transmitter might be able to send data faster than the receiver is able to process it. To cope with this, serial lines often incorporate a "handshaking" method, usually distinguished between hardware and software handshaking.
RS485: Full Duplex	off on; default: off	Turns Full Duplex mode on or off. This option is available only on the RS485 device.

Over IP

The **Over IP** serial type is used to manage serial connections over a TCP/IP network.

Instance Example

Here's an example demonstrating Over IP in action, running in Client + Server Mode. 

Serial Device Configuration

Configure serial port communication parameters in the **Serial Device Configuration** section.



Field	Value	Description
Enable	off on; default: off	Turns the instance on or off.
Name	string; default: none	Instance name, generated by the user when first creating the configuration.
Device	RS485; default: RS485	Specifies which serial port will be used for serial communication.
Baud rate (RS485)	integer [300..230400]; default: 9600	Data rate for serial data transmission (in bits per second (bps)).
Data bits	8; default: 8	Number of data bits for each character.
Stop bits	1 2; default: 1	Stop bits sent at the end of every character allow the receiving signal hardware to detect the end of a character and to resynchronise with the character stream. Electronic devices usually use one stop bit. Two stop bits are required if slow electromechanical devices are used.
Parity	None Odd Even Mark Space; default: None	In serial transmission, parity is a method of detecting errors. An extra data bit is sent with each data character, arranged so that the number of 1 bits in each character, including the parity bit, is always odd or always even. If a byte is received with the wrong number of 1s, then it must have been corrupted. However, an even number of errors can pass the parity check. <ul style="list-style-type: none">• None (N) - no parity method is used.• Odd (O) - the parity bit is set so that the number of "logical ones (1s)" has to be odd.• Even (E) - the parity bit is set so that the number of "logical ones (1s)" has to be even.
Flow control	None; default: None	In many circumstances a transmitter might be able to send data faster than the receiver is able to process it. To cope with this, serial lines often incorporate a "handshaking" method, usually distinguished between hardware and software handshaking.
RS485: Full Duplex	off on; default: off	Turns Full Duplex mode on or off. This option is available only on the RS485 device.

Over IP Configuration Settings

You can configure network related parameters of the serial connection in the **Over IP Configuration** section.



Field	Value	Description
Mode	Server Client Client + server Bidirect; default: Server	This device's role in the connection: <ul style="list-style-type: none"> • Server - the device waits for incoming connections. • Client - the device initiates the connection. • Client + server - launches service in server and client(s) mode simultaneously. • Bidirect - acts as client by default but waits for incoming connections at the same time.
Protocol	TCP UDP; default: TCP	Protocol used in the communication process.
Client : Destination address	IP Port; default: empty	Specify server address and port for client to connect to. E.g first field for address second for port. 16 destination addresses are allowed.
Server : UDP: Predefined addresses	IP Port; default: empty	Set predefined IP and port for UDP connection. E.g first field for address second for port.
Listening port	[1..65535]; default: empty	When enabled, all data will be transmitted transparently.



Field	Value	Description
Use TLS/SSL	off on; default: off	Mark to use TLS/SSL for connection.
TLS version	Support all tlsv1.0 tlsv1.1 tlsv1.2 tlsv1.3; default: Support all	Minimum TLS version allowed to be used.
TLS type	Certificate based Pre-Shared-Key based ; default: Certificate based	Select the type of TLS encryption.

Require certificate	off on; default: on	Demand certificate and key from peer and verify them against certificate authority.
Verify host	off on; default: off	Check if the server certificates Common Name (CN) matches hostname to which client is connecting.
Certificate files from device	off on; default: off	Choose this option if you want to select certificate files from device. Certificate files can be generated here .
Certificate file	.crt file; default: none	Upload certificate file.
Key file	.key file; default: none	Upload key file.
CA file	.ca file; default: none	Upload CA file.
Pre-Shared-Key	string; default: none	The pre-shared-key in hex format with no leading "0x".
Identify	string; default: none	Specify the identity.



	Field	Value	Description
Raw mode		off on; default: on	When enabled, all data will be transmitted transparently.
Remove all zeros		off on; default: off	When checked, indicates that the first hex zeros should be skipped.
Inactivity timeout		integer [0..36000]; default: 300	Specifies period of time in seconds, where server connection must be inactive, to disconnect client. To disable timeout input 0.
Serial timeout		integer [0..1000]; default: none	Specifies the maximum milliseconds to wait for serial data.
Max clients		integer [1..32]; default: 4	Specify how many clients are allowed to connect simultaneously.
TCP echo		on off; default: off	Enable software TCP echo.
Close connections		on off; default: off	Close TCP connections everytime data is sent or received (might result in serial data loss).
Keep alive		on off; default: off	Enable keep alive.
Keep alive time		integer [0..32000]; default: 0	Close TCP connections everytime data is sent or received (might result in serial data loss).
Keep alive interval		integer [0..32000]; default: 0	The interval between subsequential keepalive probes.

Keep alive probes

integer
[0..32000];
default: 0

The number of
unacknowledged probes.

IP Filter

The **IP Filter** section is used for configuring which network is allowed to communicate with the device. You may add a new instance by selecting the Interface and pressing Add.



Then enter the IP address and save.

